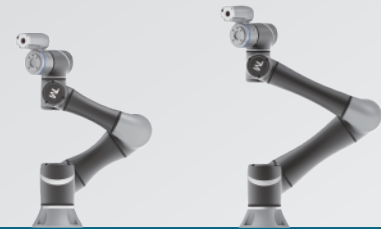


TM5

TM AI COBOT

Native AI engine + Robotic arm + Vision system

All in ONE



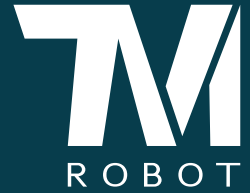
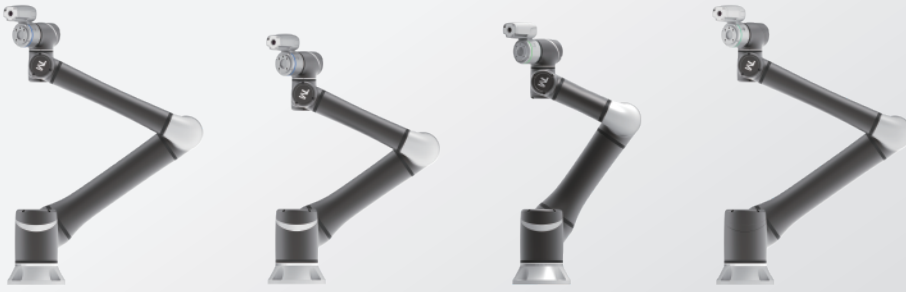
| Model | | TM5-700 | TM5-900 | TM5M-700 | TM5M-900 |
|--|-------------|---|----------|-----------|----------|
| Weight | | 22.1kg | 22.6kg | 22.1kg | 22.6kg |
| Maximum Payload | | 6kg | 4kg | 6kg | 4kg |
| Reach | | 700mm | 900mm | 700mm | 900mm |
| Joint ranges | J1,J6 | +/- 270° | +/- 270° | +/- 270° | +/- 270° |
| | J2,J4,J5 | +/- 180° | +/- 180° | +/- 180° | +/- 180° |
| | J3 | +/- 155° | | | |
| Speed | J1,J2,J3 | 180°/s | | | |
| | J4,J5,J6 | 225°/s | | | |
| Typical Speed | | 1.1m/s | 1.4m/s | 1.1m/s | 1.4m/s |
| Max. Speed | | 4 m/s | | | |
| Repeatability | | +/- 0.05 mm | | | |
| Degree Of Freedom | | 6 rotating joints | | | |
| I/O | Control box | Digital In: 16 Digital Out: 16 Analog In: 2 Analog Out: 1 | | | |
| | Tool Conn. | Digital In: 4 Digital Out: 4 Analog In: 1 Analog Out: 0 | | | |
| I/O Power Supply | | 24V 2.0A for control box 24V 1.5A for tool | | | |
| IP Classification | | IP54 (Robot Arm); IP32 (Control Box) | | | |
| Power Consumption | | Typical 220 watts | | | |
| Temperature | | The robot can work in a temperature range of 0-50°C | | | |
| Cleanliness | | ISO Class 3 | | | |
| Power Supply | | 100-240 VAC, 50-60 Hz | | 22-60 VDC | |
| I/O Interface | | 3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0 | | | |
| Communication | | RS232, Ethernet, Modbus TCP/RTU (master & slave), PROFINET (optional), EtherNet/IP (optional) | | | |
| Programming Environment | | TMflow, flowchart based | | | |
| Certification | | CE, SEMI S2 (optional) | | | |
| AI & Vision* ⁽¹⁾ | | | | | |
| AI Function | | Classification, Object Detection, Segmentation, Anomaly Detection, AI OCR | | | |
| Application | | Positioning, 1D/2D Barcode Reading, OCR, Defect Detection, Measurement, Assembly Check | | | |
| Positioning Accuracy | | 2D Positioning: 0.1 mm* ⁽²⁾ | | | |
| Eye in Hand (Built in) | | Auto-focused color camera with 5M resolution, Working distance 100 mm ~ ∞ | | | |
| Eye to Hand (Optional) | | Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera* ⁽³⁾ | | | |

* ⁽¹⁾ No built-in vision robot arms TM5X-700, TM5X-900 are also available.

* ⁽²⁾ The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.

* ⁽³⁾ Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.





TM12 / TM14 / TM16 / TM20

TM AI COBOT with built-in vision

The best and smartest choice for smart factory

| Model | TM12 | TM14 | TM16 | TM20 | TM12M | TM14M | TM16M | TM20M |
|--|--|--|----------|----------|-----------|----------|----------|----------|
| Weight | 32.8kg | 32.5kg | 32kg | 32.8kg | 32.8kg | 32.5kg | 32kg | 32.8kg |
| Maximum Payload | 12kg | 14kg | 16kg | 20kg | 12kg | 14kg | 16kg | 20kg |
| Reach | 1300mm | 1100mm | 900mm | 1300mm | 1300mm | 1100mm | 900mm | 1300mm |
| Joint ranges | J1,J6 | +/- 270° | +/- 270° | +/- 270° | +/- 270° | +/- 270° | +/- 270° | +/- 270° |
| | J2,J4,J5 | +/- 180° | +/- 180° | +/- 180° | +/- 180° | +/- 180° | +/- 180° | +/- 180° |
| | J3 | +/- 166° | +/- 163° | +/- 155° | +/- 166° | +/- 166° | +/- 163° | +/- 155° |
| Speed | J1,J2 | 120°/s | 120°/s | 120°/s | 90°/s | 120°/s | 120°/s | 120°/s |
| | J3 | 180°/s | 180°/s | 180°/s | 120°/s | 180°/s | 180°/s | 180°/s |
| | J4 | 180°/s | 150°/s | 180°/s | 150°/s | 180°/s | 150°/s | 180°/s |
| | J5 | 180°/s | 150°/s | 180°/s | 180°/s | 180°/s | 150°/s | 180°/s |
| | J6 | 180°/s | 180°/s | 180°/s | 225°/s | 180°/s | 180°/s | 225°/s |
| Typical Speed | 1.3m/s | 1.1m/s | 1.1m/s | 1.1m/s | 1.3m/s | 1.1m/s | 1.1m/s | 1.1m/s |
| Max. Speed | 4 m/s | | | | | | | |
| Repeatability | +/- 0.1 mm | | | | | | | |
| Degree Of Freedom | 6 rotation joints | | | | | | | |
| I/O | Control box | Digital In: 16 Digital Out: 16 Analog In: 2 Analog Out: 1 | | | | | | |
| | Tool Conn. | Digital In: 4 Digital Out: 4 Analog In: 1 Analog Out: 0 | | | | | | |
| I/O Power Supply | 24V 2.0A for control box and 24V 1.5A for tool | | | | | | | |
| IP Classification | IP54(Robot Arm); IP32(Control Box) | | | | | | | |
| Power Consumption | Typical 300 watts | | | | | | | |
| Temperature | The robot can work in a temperature range of 0-50°C | | | | | | | |
| Cleanliness | ISO Class 3 | | | | | | | |
| Power Supply | 100-240 VAC, 50-60 Hz | | | | 22-60 VDC | | | |
| I/O Interface | 3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0 | | | | | | | |
| Communication | RS232, Ethernet, Modbus TCP/RTU(master & slave), PROFINET(Optional), EtherNet/IP(Optional) | | | | | | | |
| Programming Environment | TMflow, flowchart based | | | | | | | |
| Certification | CE, SEMI S2 (Option) | | | | | | | |
| AI & Vision* ⁽¹⁾ | | | | | | | | |
| AI Function | Classification, Object Detection, Segmentation, Anomaly Detection, AI OCR | | | | | | | |
| Application | Positioning, 1D/2D Barcode Reading, OCR, Defect Detection, Measurement, Assembly Check | | | | | | | |
| Positioning Accuracy | 2D Positioning: 0.1 mm* ⁽²⁾ | | | | | | | |
| Eye in Hand (Built in) | Auto-focused color camera with 5M resolution, Working distance 100 mm ~ ∞ | | | | | | | |
| Eye to Hand (Optional) | Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera* ⁽³⁾ | | | | | | | |

* ⁽¹⁾ No built-in vision robot arms TM12X, TM14X, TM16X, TM20X are also available.

* ⁽²⁾ The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.

* ⁽³⁾ Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

